

JAVA DIP - ROBINSON OPERATOR

http://www.tutorialspoint.com/java_dip/applying_robinson_operator.htm

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Robinson compass masks are yet another type of derivative masks which are used for edge detection. This operator is also known as direction mask. In this operator we take one mask and rotate it in all the eight major directions to get edges of the eight directions.

We are going to use **OpenCV** function **filter2D** to apply Robinson operator to images. It can be found under **Imgproc** package. Its syntax is given below:

```
filter2D(src, dst, ddepth, kernel, anchor, delta, BORDER_DEFAULT );
```

The function arguments are described below:

Sr.No.	Argument
1	src It is source image.
2	dst It is destination image.
3	ddepth It is the depth of dst. A negative value <i>such as</i> - 1 indicates that the depth is the same as the source.
4	kernel It is the kernel to be scanned through the image.
5	anchor It is the position of the anchor relative to its kernel. The location Point-1, - 1 indicates the center by default.
6	delta It is a value to be added to each pixel during the convolution. By default it is 0.
7	BORDER_DEFAULT We let this value by default.

Apart from the filter2D method, there are other methods provided by the Imgproc class. They are described briefly:

Sr.No. Methods

1

cvtColor*Matsrc, Matdst, intcode, intdstCn*

It converts an image from one color space to another.

2

dilate*Matsrc, Matdst, Matkernel*

It dilates an image by using a specific structuring element.

3

equalizeHist*Matsrc, Matdst*

It equalizes the histogram of a grayscale image.

4

filter2D*Matsrc, Matdst, intdepth, Matkernel, Pointanchor, doubledelta*

It convolves an image with the kernel.

5

GaussianBlur*Matsrc, Matdst, Sizeksize, doublesigmaX*

It blurs an image using a Gaussian filter.

6

integral*Matsrc, Matsum*

It calculates the integral of an image.

Example

The following example demonstrates the use of Imgproc class to apply Robinson operator to an image of Grayscale.

```
import org.opencv.core.Core;
import org.opencv.core.CvType;
import org.opencv.core.Mat;

import org.opencv.highgui.Highgui;
import org.opencv.imgproc.Imgproc;

public class convolution {
    public static void main( String[] args ){

        try {
            int kernelSize = 9;
            System.loadLibrary( Core.NATIVE_LIBRARY_NAME );

            Mat source = Highgui.imread("grayscale.jpg", Highgui.CV_LOAD_IMAGE_GRAYSCALE);
            Mat destination = new Mat(source.rows(),source.cols(), source.type());

            Mat kernel = new Mat(kernelSize,kernelSize, CvType.CV_32F){
                {
                    put(0,0,-1);
                    put(0,1,0);
                    put(0,2,1);

                    put(1,0-2);
                    put(1,1,0);
                }
            }
        }
    }
}
```

```

        put(1, 2, 2);

        put(2, 0, -1);
        put(2, 1, 0);
        put(2, 2, 1);
    };
};

Imgproc.filter2D(source, destination, -1, kernel);
Highgui.imwrite("output.jpg", destination);

} catch (Exception e) {
    System.out.println("Error: " + e.getMessage());
}
}
}

```

Output

When you execute the given code, the following output is seen:

Original Image



This original image is convolved with the Robinson operator of North edges as given below:

North Direction Mask

```

-1  0  1
-2  0  2
-1  0  1

```

Convolved Image *RobinsonNorth*

This original image has also been convolved with the Robinson operator of East edges as given below:

East Direction Mask

$$\begin{bmatrix} -1 & -2 & -1 \\ 0 & 0 & 0 \\ 1 & 2 & 1 \end{bmatrix}$$

Convolved Image*RobinsonEast*